

A brief introduction to the problem of estimating the number of sinusoids, M

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We are given a set of data consisting of a superposition of M sinusoids and random Gaussian noise. The problem is to determine the number of sinusoids M , for which there is the greatest evidence or in essence the most probable value of M . We approach the problem using the techniques of Bayesian hypothesis testing.

We begin by considering the given data set $\{D_k\}$:

$$\{D_k\} = \sum_{i=1}^m A_i \sin \omega_i t_k + \phi_i + n_i \quad (1)$$

where $\{A_i\}$ is the set of amplitudes, $\{\omega_i\}$ is the set of frequencies and $\{\phi_i\}$ is the set of phases. The Gaussian noise is $\{n_i\}$ and t_k refers to the k time samples which give the data set $\{D_k\}$.

Our model data for a particular amplitude, frequency and phase under consideration would be

$$F_k = \sum_{i=1}^m A_i \sin \omega_i t_k + \phi_i. \quad (2)$$

In order to determine the number of sinusoids M , we need to estimate the probability distribution for M or alternatively we need to estimate :

$$\text{prob}(M/\{D_k\}, I) \quad (3)$$

where the notation means that we are considering the probability of M given the data set $\{D_k\}$ and any prior information that we may have I .

We begin with Bayes' theorem

$$\text{prob}(M/\{D_k\}, I) = \frac{\text{prob}(\{D_k\}/M, I) \times \text{prob}(M/I)}{\text{prob}(\{D_k\}/I)}. \quad (4)$$

$\text{prob}(M/I)$ is called the prior, $\text{prob}(\{D_k\}/M, I)$ is called the likelihood, $\text{prob}(M/\{D_k\}, I)$ is the posterior and $\text{prob}(\{D_k\}/I)$ is called the evidence.

At the outset, we assign a uniform prior from $M = 0$ up to a maximum value of $M = M_{\max}$. Hence :

$$\text{prob}(M/I) = \frac{1}{M_{\max}}. \quad (5)$$

We can determine the evidence $\text{prob}(\{D_k\}/I)$ at a later stage using the normalisation condition

$$\text{prob} \sum (M/\{D_k\}, I) = 1. \quad (6)$$

Next let us consider the likelihood :

$$\text{prob}(\{D_k\}/M, I) = \int \dots \int \text{prob}(\{D_k\}, \{A_i, \omega_i, \phi_i\}/M, I) d^M A_i d^M \omega_i d^M \phi_i \quad (7)$$

expressing it as a marginal integral over the parameters of the model.

$$\text{prob}(\{D_k\}, \{A_i, \omega_i, \phi_i\}/M, I) = \text{prob}(\{D_k\}/\{A_i, \omega_i, \phi_i\}, M, I) \times \text{prob}(\{A_i, \omega_i, \phi_i\}/M, I) \quad (8)$$

from the ‘product rule’ of probabilities.

Hence :

$$\begin{aligned} \text{prob}(\{D_k\}/M, I) &= \int \dots \int \text{prob}(\{D_k\}/\{A_i, \omega_i, \phi_i\}, M, I) \times \text{prob}(\{A_i, \omega_i, \phi_i\}/M, I) \\ &\quad d^M A_i d^M \omega_i d^M \phi_i. \end{aligned} \quad (9)$$

Once again, we shall assign a uniform prior to A_i , ω_i and ϕ_i while recognising the fact that the phase ϕ should lie between 0 and 2π .

$$\text{prob}(\{A_i, \omega_i, \phi_i\}/M, I) = \frac{1}{[2\pi A_{\max} \omega_{\max}]^M} \quad (10)$$

The likelihood function demands a more involved treatment. Before starting it is worth reiterating that F_k represents the model data and $\{D_k\}$ represents the actual data.

Once again we start with Bayes’ theorem :

$$\text{prob}(F_k/\{D_k\}, I) \propto \text{prob}(\{D_k\}/F_k, I) \times \text{prob}(F_k/I). \quad (11)$$

Once more we shall assign a uniform prior, thus arriving at the equation

$$\text{prob}(F_k/\{D_k\}, I) \propto \text{prob}(\{D_k\}/F_k, I). \quad (12)$$

We assume that each individual datum D_k is independent. Therefore we can say :

$$\text{prob}(\{D_k\}/F_k, I) = \prod_{k=1}^N \text{prob}(D_k/F_k, I) \quad (13)$$

We also assume that the noise associated with each datum can be represented by a Gaussian

$$\text{prob}(\{D_k\}/F_k, I) = \frac{1}{\sigma_k \sqrt{2\pi}} \exp\left[-\frac{(F_k - D_k)^2}{2\sigma^2}\right]. \quad (14)$$

Using the above calculation, in the context of our problem :

$$\text{prob}(\{D_k\}/\{A_i, \omega_i, \phi_i\}, M, I) \propto \exp\left(\frac{-\chi^2}{2}\right). \quad (15)$$

where

$$\chi^2 = \sum_{k=1}^N \left(\frac{F_k - D_k}{\sigma_k}\right)^2. \quad (16)$$

Finally we have :

$$\text{prob}(M/\{D_k\}, I) \propto \frac{1}{(2\pi A_{\max} \omega_{\max})^M} \int \dots \int \exp\left(\frac{-\chi^2}{2}\right) d^M A_i \, d^M \omega_i \, d^M \phi_i. \quad (17)$$