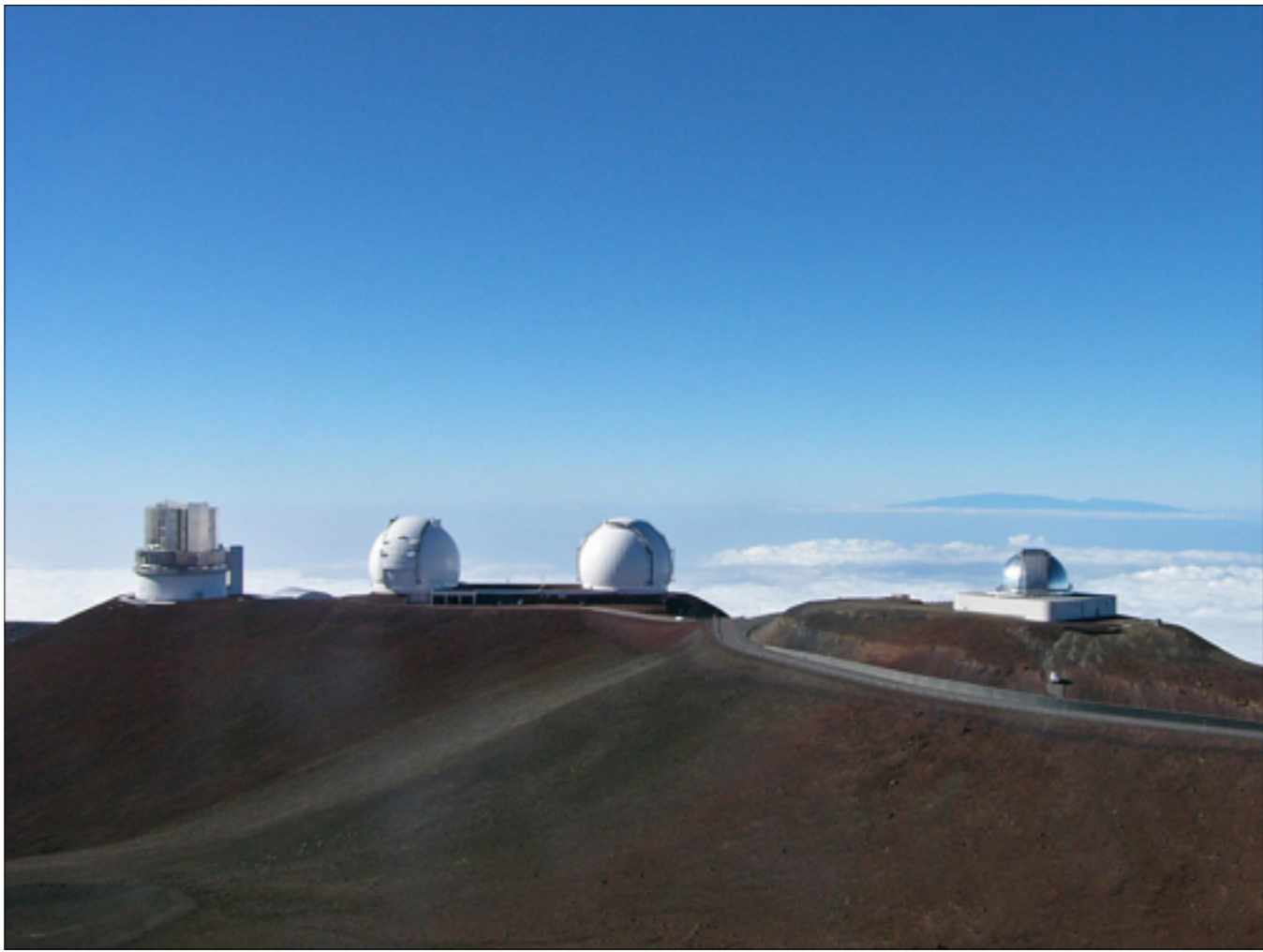


# **Classical mechanics from the mountaintop**

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AXIOMATA,

SIVE

LEGES MOTUS.

LEX I.

(\*) Corpus sine periculis in statu suo quiescendi vel movendi uniformiter in directam, nisi quatenus a viribus impressis cogitur statum illum mutare.

PROJECTILIA perseverant in motibus suis, nisi quatenus a resistentiis aeris retardantur, et vi gravitatis impellantur deorsum. Trochus, cujus partes obvolvendo perpetuo retrahunt sese a motibus rectilineis, non cessat rotari, nisi quatenus ab aere retardatur. Majora autem Planetarum et Cometarum corpora motus suos et progressivos et circulares in spatiis minus resistentiis factis conservant distinctis.

LEX II.

(\*) Mutationem motus proportionalem esse vi motrici impressae, et fieri secundum lineam rectam quae vi illi imprimitur.

Si vis aliqua motum quemvis generet; dupla duplata, tripla triplata generabit, sive simul et semel, sive gradatim et successivè impressa fuerit. Ex his motus (quoniam in eandem semper plagam cum vi gener-

[1] 24. Ex his patet lege quam [2] demonstravimus, sequitur motum motum esse constantem et uniformem, adhaec nec illius accelerationem, nec decelerationem, nec qualemvis obstructionem mobili offerunt; Unde rursus projectilia motum suum servare solent, quatenus est aliquid huiusmodi retardantis casus. Cum autem corpora projecta vel per medium viscosum deferantur, vel etiam super aliosum superponitur superficies viscosa incidenti, et vi gravitatis deorsum semper urgentur, necesse est ut motus ambiant motus vel partem quam in linea obstructione superanda constanti abstant, ac prout major vel minor est illi resistentiis, vel major vel minor decelerationem scribit corpora projecta velocitas. Ex his igitur patet

motus planetarum et cometarum corpora nullam ambulationem in spatiis resistentiis experiri resistunt, cum motus sui directione conservent. [2] 25. Si corpus vi aëria, quae est vi gravitatis, successivè eandem aut parallelam directionem constanti impingatur, motus illius constanti acceleratur; nam per leg. 1. motus constanti accipitur, et per leg. 2. nova compingitur constanti additur. Si vero aliqua vis in corpus jam motum constanti directione perpetuè agit, motus illius constanti retardatur, per leg. 2. Si vis compingatur constanti ac uniformiter agit, illi est, si constanti sit, corpus vel vi impulsione, aequalibus temporibus aequalia accipit velocitatis incrementa, sive motu uniformiter accelerato ferat, et coloratum vi illi accipitur, sicut ut tempora quibus

atrica determinatur) si corpus antea movebatur, motus ejus vel compingenti additur, vel contrario subducitur, vel obliquè obliquè adjectur, et cum eo secundum utriusque determinationem compositur.

(\*) LEX III.

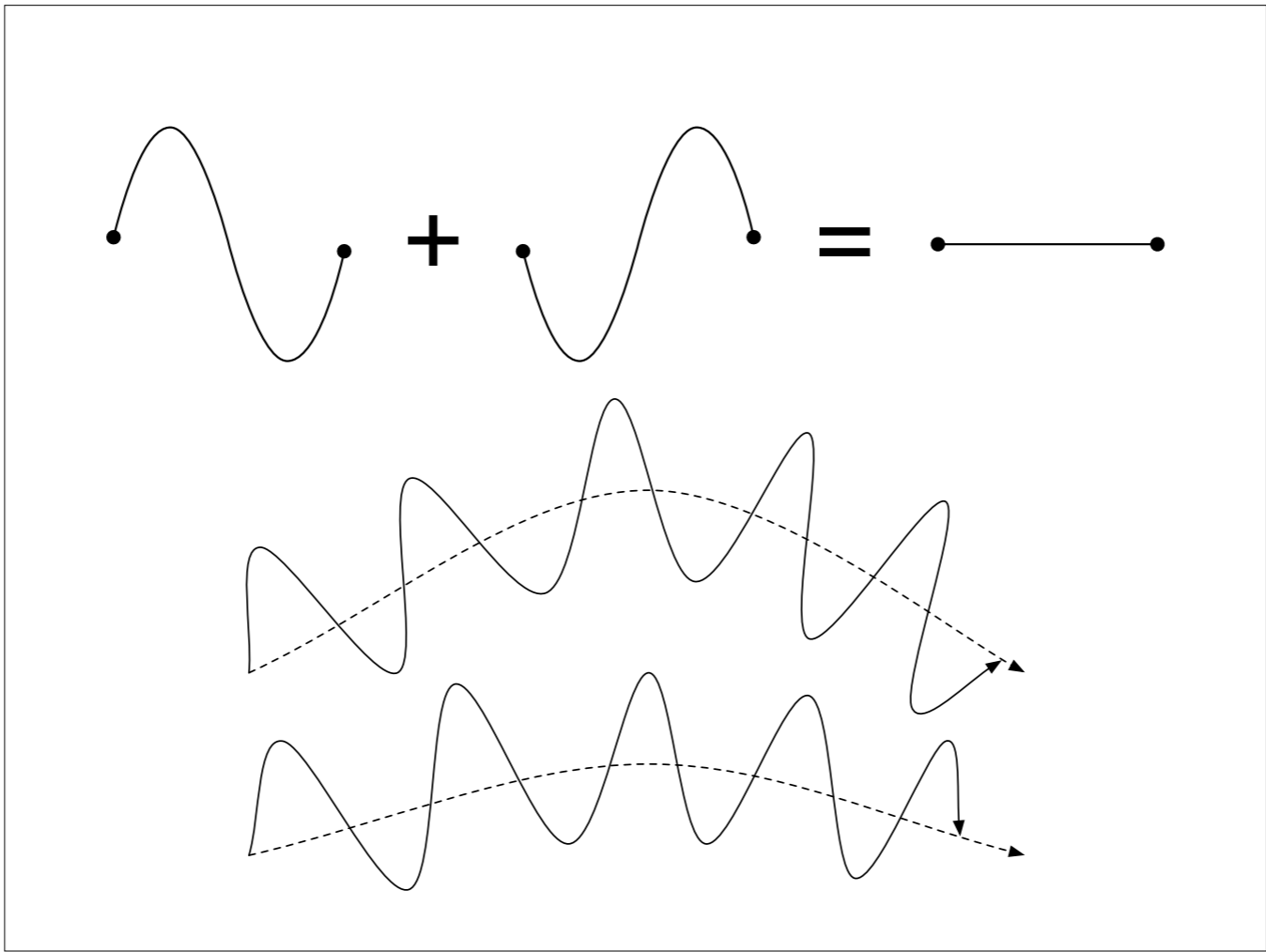
Actioni contrariam semper et æqualem esse reactionem: sive corporum duorum actiones in se mutuo semper esse æquales et in partes contrarias dirigi.

Quicquid premit vel trahit alterum, tantum ab eo premitur vel trahitur. Si quis lapidem digito premit, premitur et huius digitus a lapide. Si equus lapidem fusi alligatum trahit, retrahetur etiam et equus (ut ita dicam) æqualiter in lapidem: nam fusi utriusque distensus eodem relaxandi se conatu urgebit equum versus lapidem, ac lapidem versus equum; tantumque impellet progressum unius quantum promovet progressum alterius. Si corpus aliquod in corpus aliud impingens, motum ejus vi sua quomodocumque mutaverit, idem quoque vicissim in motu proprio eandem

generatum. At si vis constanti constanti agit, aequalibus temporibus aequalia sunt colorata deceleratione, et corpus motu uniformiter retardatur. Generaliter tandem, si corpus quicquid vel sive constanti sive variabili constanti impingatur, et distenso vel relaxato quomodo vis illius actione constanti accipitur, constanti deceleratione vel illius reactione proficitur, ut vis illius sua veligit, corpus illud in se et recte suo eodem habetis retardatur, vel ad eandem viam suam pergit, modo et subducendo periculis; adhaec motum retrahendo non ambiat, nisi rursus premitur ad punctum ex quo egressus fuit motus; nam eandem vi in se et recte corpus, aequalibus temporibus aequalia colorata gradus generat et recipit [2].

[2] Corpus gravitatis in terra vicinè, adhaec motu uniformiter accelerato deceleratur, et motu uniformiter retardatur acceleratur. . . . Demonstratio . . . Similitudinem motus uniformiter accelerati motu uniformiter retardati, sive eandem illius in subjectum platum premit, tum in vertice, tum in radice motus; aut eandem pendens, sive via motus [3] ut motus in via gravitatis acceleratiore ducta; egiß eandem quidem corpora motu eandem in vertice et in radice motu periculis, manebit etiam eandem via acceleratiore gravitatis. Itaque corpora gravitatis in radice et vertice motu aequalia quibus temporibus periculis, colorata aëria retardantur, ut acceleratiore motus ut experientur. [3] motus est igitur via acceleratiore, et per hanc ad hanc perpendicularem [2] uniformiter agit; gravitatis ergo motu uniformiter accelerato deceleratur, et uniformiter retardatur acceleratur [2]. Q. n. d.

[2] Similitudinem motus uniformiter accelerati motu uniformiter retardati, sive eandem illius in subjectum platum premit, tum in vertice, tum in radice motus; aut eandem pendens, sive via motus [3] ut motus in via gravitatis acceleratiore ducta; egiß eandem quidem corpora motu eandem in vertice et in radice motu periculis, manebit etiam eandem via acceleratiore gravitatis. Itaque corpora gravitatis in radice et vertice motu aequalia quibus temporibus periculis, colorata aëria retardantur, ut acceleratiore motus ut experientur. [3] motus est igitur via acceleratiore, et per hanc ad hanc perpendicularem [2] uniformiter agit; gravitatis ergo motu uniformiter accelerato deceleratur, et uniformiter retardatur acceleratur [2]. Q. n. d.



Fermat's principle

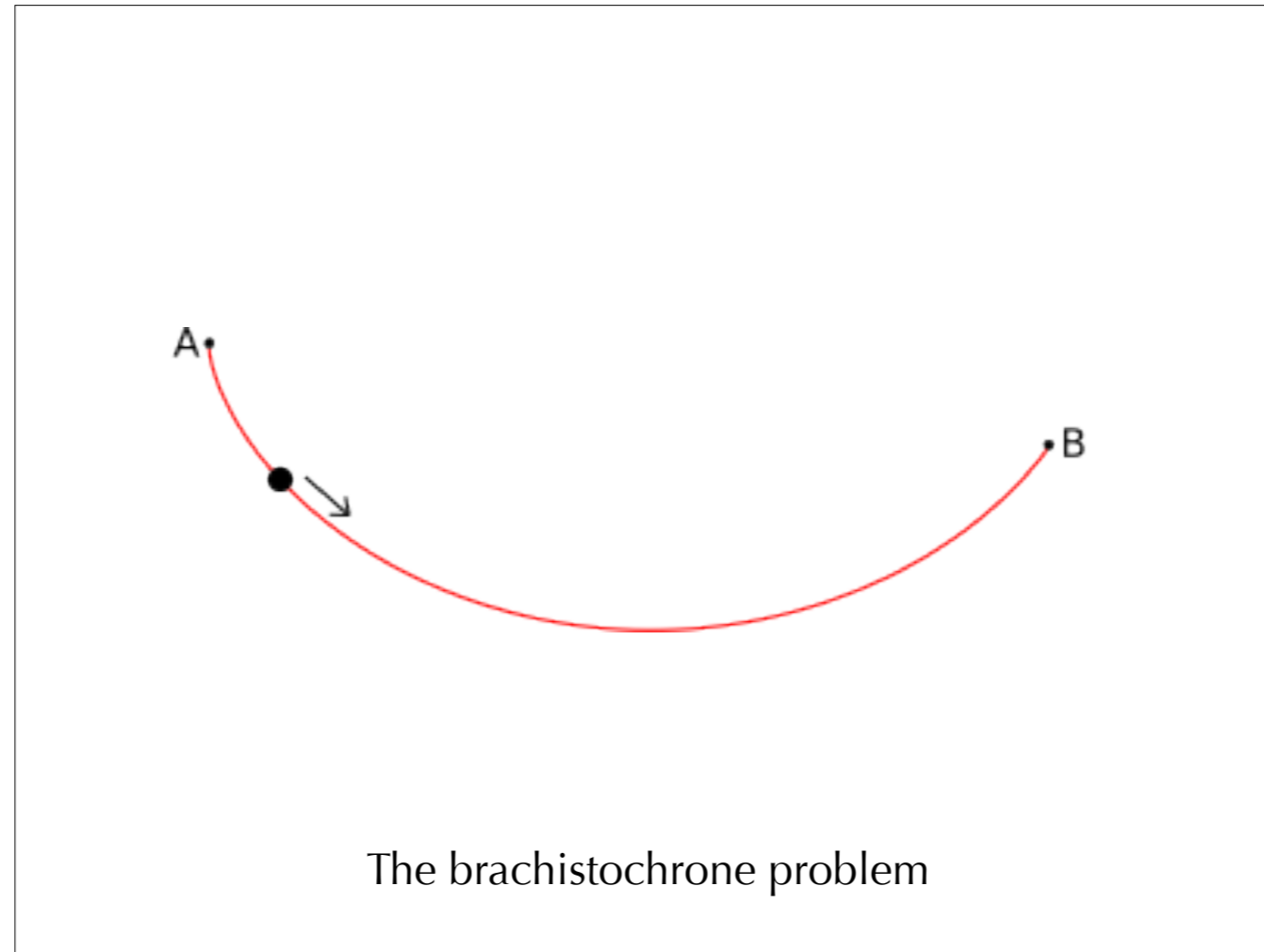


Travel time gets shorter as you go from the first to the second,  
then it gets longer.  
The minimum is at the shortest path





Catenary  
Can describe it in terms of balance of forces  
but also minimising total potential energy



Brachistochrone problem  
Very similar to the tautochrone problem, solved by Huygens in 1659  
Johann Bernoulli, 1696 (first published 'integral')  
Led to the calculus of variations

The Lagrangian

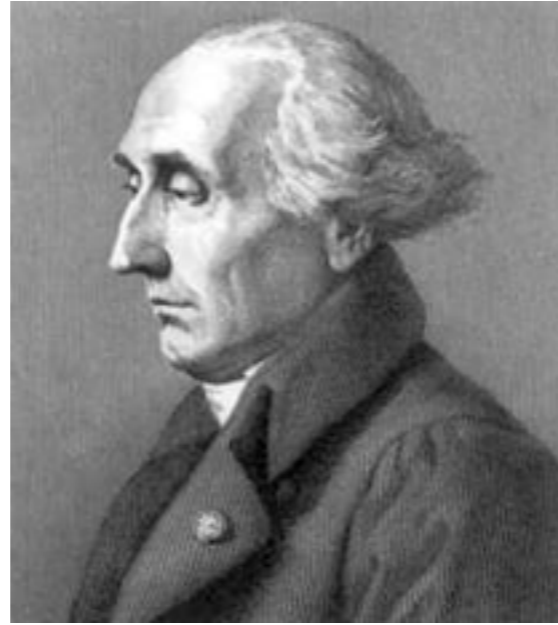
$$L = T - V$$

$$S = \int L dt$$

The action

Hamilton's principle





Joseph Louis Lagrange (1736–1813)  
William Rowan Hamilton (1805–1865)

$$*H* = *T* + *V*$$

$$\dot{p}_i = -\frac{\partial H}{\partial q_i}$$
$$\dot{q}_i = +\frac{\partial H}{\partial p_i}$$

Describes motion in a  $2n$ -dimensional space

But this tells us that only  $2 \times 3 = 6$  numbers completely characterise motion in 3-d space.

Also, this is true for more than just particle mechanics.

Leads to Newton's equations, Maxwell's, Schrödinger's; electrical and acoustic systems.

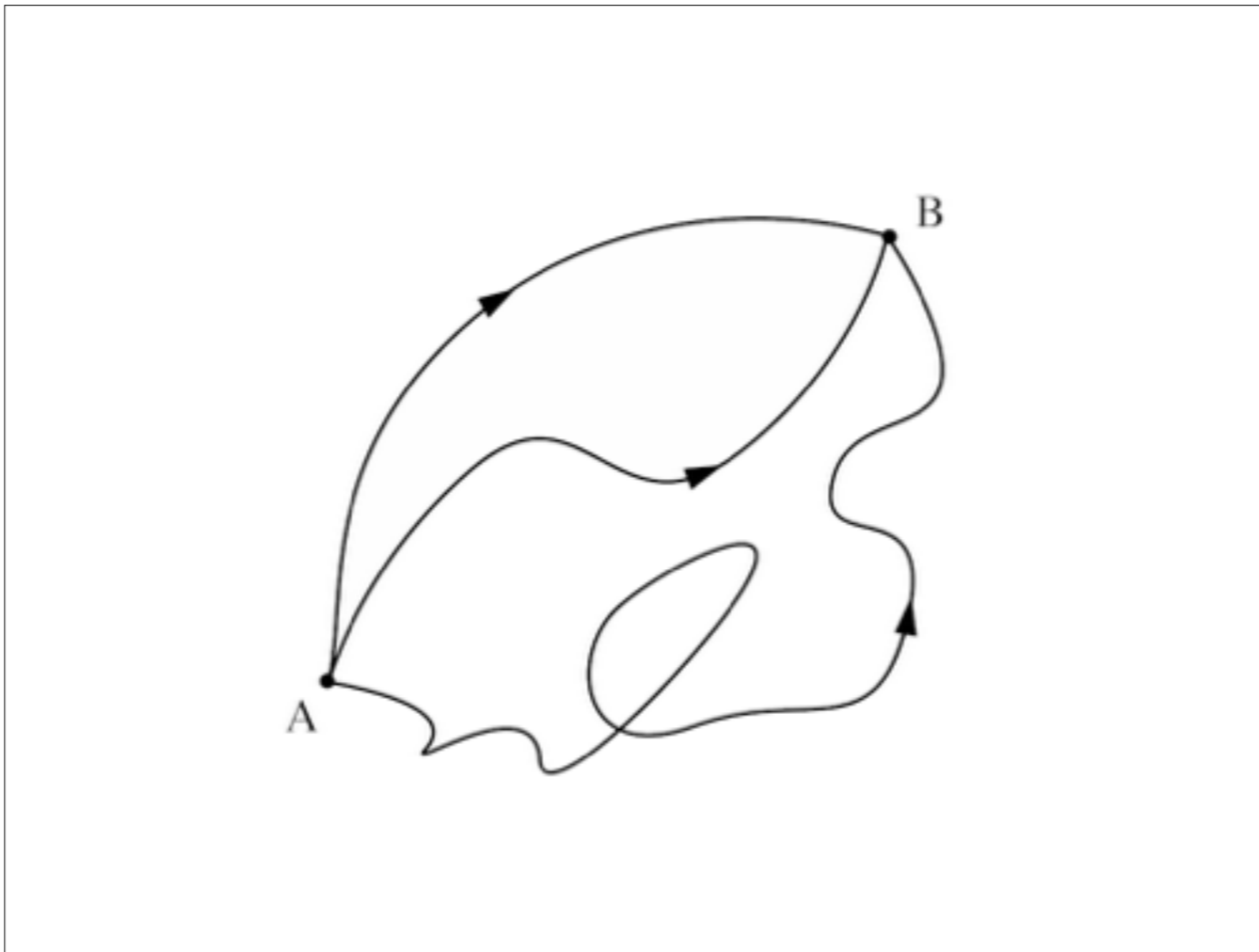
Not always useful for actual calculations, though

$$i\hbar \frac{\partial}{\partial t} \psi = \hat{H} \psi$$

$$\hat{H} \psi = E \psi$$

Schrödinger equation (one form of it)

Similarly, it's the classical theory of fields (based on continuous Lagrangians) which is used as the basis for quantum field theory



Feynman path-integral formulation  
(building on work by Dirac)  
Each path is weighted by  $\exp(iS/\hbar)$

$$\dot{p}_i = -\frac{\partial H}{\partial q_i}$$
$$\dot{q}_i = +\frac{\partial H}{\partial p_i}$$

If H indep of q, then p is conserved



Emmy Noether (1882–1935)

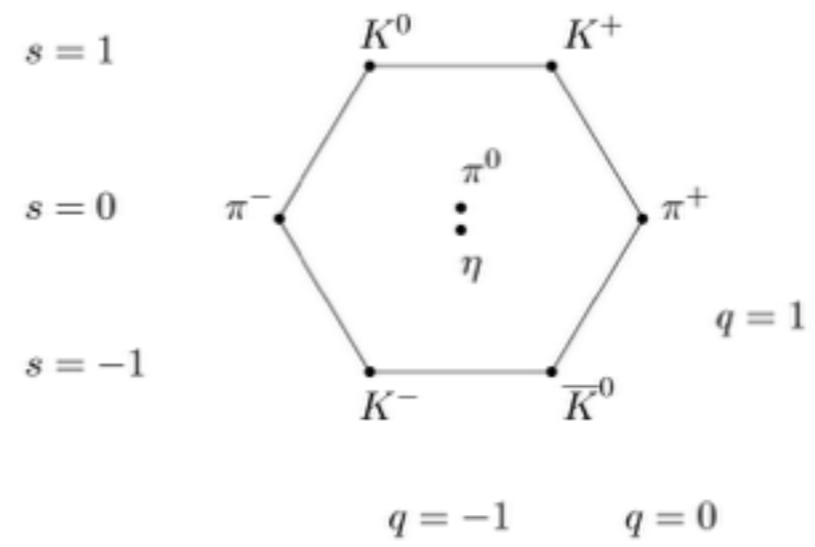


**Noether's theorem**

For each symmetry of the Lagrangian,  
there is a conserved quantity

$$\begin{aligned}
L = & -\frac{1}{2}\partial_\nu g_\mu^a \partial_\nu g_\mu^a - g_s f^{abc} \partial_\mu g_\nu^a g_\mu^b g_\nu^c - \frac{1}{4}g_s^2 f^{abc} f^{ade} g_\mu^b g_\nu^c g_\mu^d g_\nu^e + \frac{1}{2}ig_s^2 (q_i^\tau \gamma^\mu q_j^\tau) g_\mu^a + \bar{C}^a \partial^2 G^a + \\
& g_s f^{abc} \partial_\mu \bar{C}^a G^b g_\mu^c - \partial_\nu W_\mu^+ \partial_\nu W_\mu^- - M^2 W_\mu^+ W_\mu^- - \frac{1}{2}\partial_\nu Z_\mu^0 \partial_\nu Z_\mu^0 - \frac{1}{2c_w^2} M^2 Z_\mu^0 Z_\mu^0 - \frac{1}{2}\partial_\mu A_\nu \partial_\mu A_\nu - \\
& \frac{1}{2}\partial_\mu H \partial_\mu H - \frac{1}{2}m_h^2 H^2 - \partial_\mu \phi^+ \partial_\mu \phi^- - M^2 \phi^+ \phi^- - \frac{1}{2}\partial_\mu \phi^0 \partial_\mu \phi^0 - \frac{1}{2c_w^2} M \phi^0 \phi^0 - \beta_h \frac{[2M^2 + \frac{2M}{g} H + \\
& \frac{1}{2}(H^2 + \phi^0 \phi^0 + 2\phi^+ \phi^-)] + \frac{2M^4}{g^2} \alpha_h - igc_w [\partial_\nu Z_\mu^0 (W_\mu^+ W_\nu^- - W_\nu^+ W_\mu^-) - Z_\nu^0 (W_\mu^+ \partial_\nu W_\mu^- - \\
& W_\mu^- \partial_\nu W_\mu^+) + Z_\nu^0 (W_\nu^+ \partial_\mu W_\mu^- - W_\mu^- \partial_\nu W_\nu^+)] - ig s_w [\partial_\nu A_\mu (W_\mu^+ W_\nu^- - W_\nu^+ W_\mu^-) - A_\nu (W_\mu^+ \partial_\nu W_\mu^- - \\
& W_\mu^- \partial_\nu W_\mu^+) + A_\mu (W_\nu^+ \partial_\nu W_\mu^- - W_\nu^- \partial_\nu W_\mu^+)] - \frac{1}{2}g^2 W_\mu^+ W_\mu^- W_\nu^+ W_\nu^- + \frac{1}{2}g^2 W_\mu^+ W_\nu^- W_\mu^+ W_\nu^- + \\
& g^2 c_w^2 (Z_\mu^0 W_\mu^+ Z_\nu^0 W_\nu^- - Z_\mu^0 Z_\nu^0 W_\mu^+ W_\nu^-) + g^2 s_w^2 (A_\mu W_\mu^+ A_\nu W_\nu^- - A_\mu A_\nu W_\mu^+ W_\nu^-) + \\
& g^2 s_w c_w [A_\mu Z_\nu^0 (W_\mu^+ W_\nu^- - W_\nu^+ W_\mu^-) - 2A_\mu Z_\mu^0 W_\nu^+ W_\nu^-] - g\alpha [H^3 + H\phi^0 \phi^0 + 2H\phi^+ \phi^-] - \\
& \frac{1}{8}g^2 \alpha_h [H^4 + (\phi^0)^4 + 4(\phi^+ \phi^-)^2 + 4(\phi^0)^2 \phi^+ \phi^- + 4H^2 \phi^+ \phi^- + 2(\phi^0)^2 H^2] - gM W_\mu^+ W_\mu^- H - \\
& \frac{1}{2}g \frac{M}{c_w^2} Z_\mu^0 Z_\mu^0 H - \frac{1}{2}ig [W_\mu^+ (\phi^0 \partial_\mu \phi^- - \phi^- \partial_\mu \phi^0) - W_\mu^- (\phi^0 \partial_\mu \phi^+ - \phi^+ \partial_\mu \phi^0)] + \frac{1}{2}g [W_\mu^+ (H \partial_\mu \phi^- - \\
& \phi^- \partial_\mu H) - W_\mu^- (H \partial_\mu \phi^+ - \phi^+ \partial_\mu H)] + \frac{1}{2}g \frac{1}{c_w} (Z_\mu^0 (H \partial_\mu \phi^0 - \phi^0 \partial_\mu H) - ig \frac{s_w^2}{c_w} M Z_\mu^0 (W_\mu^+ \phi^- - \\
& W_\mu^- \phi^+) + ig s_w M A_\mu (W_\mu^+ \phi^- - W_\mu^- \phi^+) - ig \frac{1-2c_w^2}{2c_w} Z_\mu^0 (\phi^+ \partial_\mu \phi^- - \phi^- \partial_\mu \phi^+) + ig s_w A_\mu (\phi^+ \partial_\mu \phi^- - \\
& \phi^- \partial_\mu \phi^+) - \frac{1}{4}g^2 W_\mu^+ W_\mu^- [H^2 + (\phi^0)^2 + 2\phi^+ \phi^-] - \frac{1}{4}g^2 \frac{1}{c_w} Z_\mu^0 [H^2 + (\phi^0)^2 + 2(2s_w^2 - 1)^2 \phi^+ \phi^-] - \\
& \frac{1}{2}g^2 \frac{s_w^2}{c_w} Z_\mu^0 \phi^0 (W_\mu^+ \phi^- + W_\mu^- \phi^+) - \frac{1}{2}ig^2 \frac{s_w^2}{c_w} Z_\mu^0 H (W_\mu^+ \phi^- - W_\mu^- \phi^+) + \frac{1}{2}g^2 s_w A_\mu \phi^0 (W_\mu^+ \phi^- + \\
& W_\mu^- \phi^+) + \frac{1}{2}ig^2 s_w A_\mu H (W_\mu^+ \phi^- - W_\mu^- \phi^+) - g^2 \frac{s_w}{c_w} (2c_w^2 - 1) Z_\mu^0 A_\mu \phi^+ \phi^- - g^1 s_w^2 A_\mu A_\mu \phi^+ \phi^- - \\
& e^\lambda (\gamma \partial + m_e^\lambda) e^\lambda - \bar{\nu}^\lambda \gamma \partial \nu^\lambda - \bar{u}_j^\lambda (\gamma \partial + m_u^\lambda) u_j^\lambda - \bar{d}_j^\lambda (\gamma \partial + m_d^\lambda) d_j^\lambda + ig s_w A_\mu [-(\bar{e}^\lambda \gamma^\mu e^\lambda) + \\
& \frac{2}{3}(\bar{u}_j^\lambda \gamma^\mu u_j^\lambda) - \frac{1}{3}(\bar{d}_j^\lambda \gamma^\mu d_j^\lambda)] + \frac{ig}{4c_w} Z_\mu^0 [(\bar{\nu}^\lambda \gamma^\mu (1 + \gamma^5) \nu^\lambda) + (\bar{e}^\lambda \gamma^\mu (4s_w^2 - 1 - \gamma^5) e^\lambda) + (\bar{u}_j^\lambda \gamma^\mu (\frac{4}{3}s_w^2 - \\
& 1 - \gamma^5) u_j^\lambda) + (\bar{d}_j^\lambda \gamma^\mu (1 - \frac{8}{3}s_w^2 - \gamma^5) d_j^\lambda)] + \frac{ig}{2\sqrt{2}} W_\mu^+ [(\bar{\nu}^\lambda \gamma^\mu (1 + \gamma^5) e^\lambda) + (\bar{u}_j^\lambda \gamma^\mu (1 + \gamma^5) C_{\lambda\kappa} d_j^\kappa)] + \\
& \frac{ig}{2\sqrt{2}} W_\mu^- [(\bar{e}^\lambda \gamma^\mu (1 + \gamma^5) \nu^\lambda) + (\bar{d}_j^\kappa C_{\lambda\kappa}^\dagger \gamma^\mu (1 + \gamma^5) u_j^\lambda)] + \frac{ig}{2\sqrt{2}} \frac{m_\lambda^2}{M} [-\phi^+ (\bar{\nu}^\lambda (1 - \gamma^5) e^\lambda) + \phi^- (\bar{e}^\lambda (1 + \\
& \gamma^5) \nu^\lambda)] - \frac{g}{2} \frac{m_\lambda^2}{M} [H (\bar{e}^\lambda e^\lambda) + i\phi^0 (\bar{e}^\lambda \gamma^5 e^\lambda)] + \frac{ig}{2M\sqrt{2}} \phi^+ [-m_d^\lambda (\bar{u}_j^\lambda C_{\lambda\kappa} (1 - \gamma^5) d_j^\kappa) + m_u^\lambda (\bar{u}_j^\lambda C_{\lambda\kappa} (1 + \\
& \gamma^5) d_j^\kappa) + \frac{ig}{2M\sqrt{2}} \phi^- [m_d^\lambda (\bar{d}_j^\kappa C_{\lambda\kappa}^\dagger (1 + \gamma^5) u_j^\kappa) - m_u^\lambda (\bar{d}_j^\kappa C_{\lambda\kappa}^\dagger (1 - \gamma^5) u_j^\kappa) - \frac{g}{2} \frac{m_\lambda^2}{M} H (\bar{u}_j^\lambda u_j^\lambda) - \\
& \frac{g}{2} \frac{m_\lambda^2}{M} H (\bar{d}_j^\lambda d_j^\lambda) + \frac{ig}{2} \frac{m_\lambda^2}{M} \phi^0 (\bar{u}_j^\lambda \gamma^5 u_j^\lambda) - \frac{ig}{2} \frac{m_\lambda^2}{M} \phi^0 (\bar{d}_j^\lambda \gamma^5 d_j^\lambda) + \bar{X}^+ (\partial^2 - M^2) X^+ + \bar{X}^- (\partial^2 - \\
& M^2) X^- + \bar{X}^0 (\partial^2 - \frac{M^2}{c_w^2}) X^0 + \bar{Y} \partial^2 Y + igc_w W_\mu^+ (\partial_\mu \bar{X}^0 X^- - \partial_\mu \bar{X}^+ X^0) + ig s_w W_\mu^+ (\partial_\mu \bar{Y} X^- - \\
& \partial_\mu \bar{X}^+ Y) + igc_w W_\mu^- (\partial_\mu \bar{X}^- X^0 - \partial_\mu \bar{X}^0 X^+) + ig s_w W_\mu^- (\partial_\mu \bar{X}^- Y - \partial_\mu \bar{Y} X^+) + \\
& igc_w Z_\mu^0 (\partial_\mu \bar{X}^+ X^- - \partial_\mu \bar{X}^- X^+) + ig s_w A_\mu (\partial_\mu \bar{X}^+ X^+ - \partial_\mu \bar{X}^- X^-) - \frac{1}{2}gM [\bar{X}^+ X^+ H + \\
& \bar{X}^- X^- H + \frac{1}{c_w^2} \bar{X}^0 X^0 H] + \frac{1-2c_w^2}{2c_w} igM [\bar{X}^+ X^0 \phi^+ - \bar{X}^- X^0 \phi^-] + \frac{1}{2c_w} igM [\bar{X}^0 X^- \phi^+ - \\
& \bar{X}^0 X^+ \phi^-] + igM s_w [\bar{X}^0 X^- \phi^+ - \bar{X}^0 X^+ \phi^-] + \frac{1}{2}igM [\bar{X}^+ X^+ \phi^0 - \bar{X}^- X^- \phi^0]
\end{aligned}$$

The standard model of particle physics



Eightfold way - meson octet.  
Murray Gell-Mann

