

# Orbit determination for extra-solar planetary systems. Lecture II

Andrzej J, Maciejewski

Institute of Astronomy, University of Zielona Góra, Poland

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# Outline

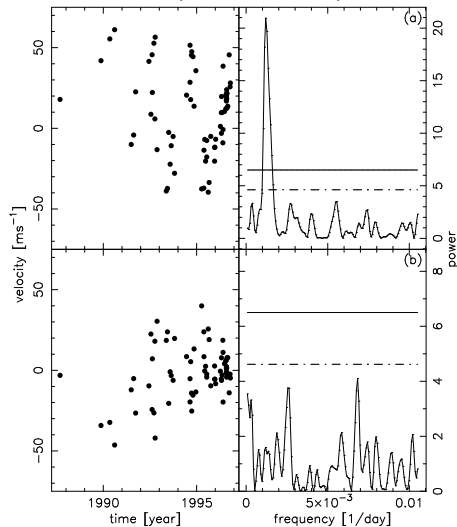
- 1 Warning example
- 2 The stability razor
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- 4 HD 202206
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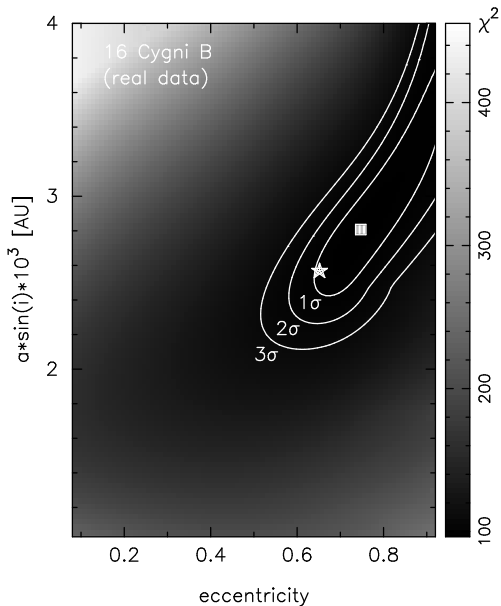
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# A planet around 16 Cygni B.

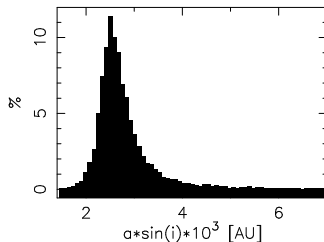
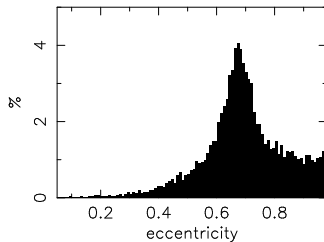
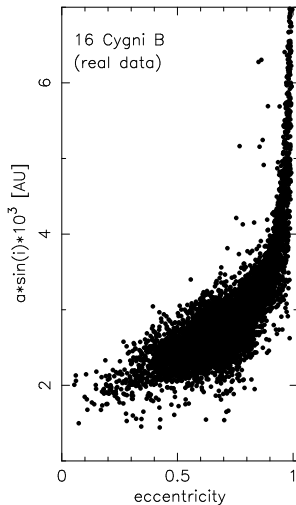
Cochran W. D., Hatzes A. P., Butler R. P., Marcy G. W., 1997, ApJ, 483, 457.



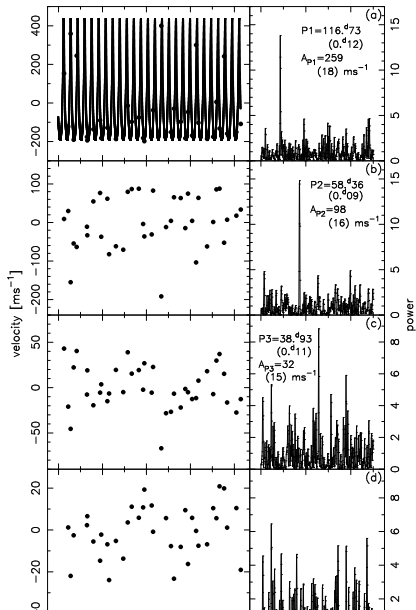
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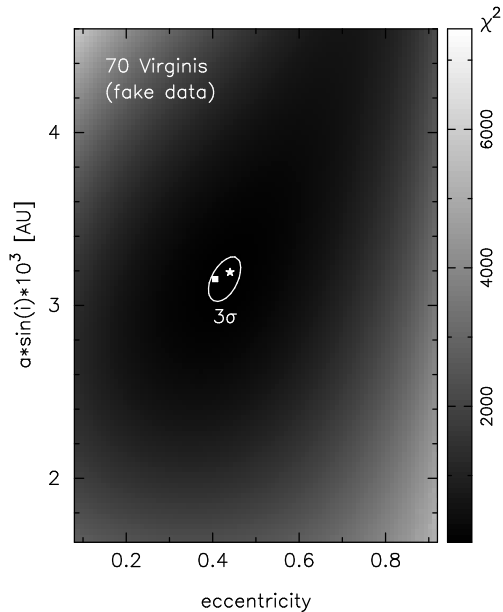
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# A planet around 70 Virginis.



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# Serious problems

- By the way, what is the number of planets. (Ockham's razor)
- Do all good fits are equally good?
- Can we predict parameters of an additional planet from a linear trend.
- Mass determinations from rv observations.

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# The stability razor

The most important observable: the fact that the planetary system exists!

The true problem is: find  $\mathbf{p}_0$  such that

$$\chi^2(\mathbf{p}_0) = \min_{\mathbf{p} \in \mathcal{S}} \chi^2(\mathbf{p})$$

$$\mathcal{S} \subset \mathbb{R}^k,$$

$\mathcal{S}$  is a subset of the parameters space corresponding to stable systems

# Two approaches

- 1 First fit then check and correct.
- 2 Check while fitting.

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# How to measure stability?

Lyapunov exponent

$$\frac{d}{dt}\mathbf{x} = \mathbf{v}(\mathbf{x}), \quad \frac{d}{dt}\boldsymbol{\delta} = \frac{\partial \mathbf{v}}{\partial \mathbf{x}}(\mathbf{x})\boldsymbol{\delta}, \quad \mathbf{x}, \boldsymbol{\delta} \in \mathbb{R}^n,$$

$$\mathbf{x}(t_0) = \mathbf{x}_0, \quad \boldsymbol{\delta}(t_0) = \boldsymbol{\delta}_0 \neq \mathbf{0},$$

Definition

$$\lambda = \lambda(\mathbf{x}_0, \boldsymbol{\delta}_0) = \lim_{t \rightarrow \infty} \frac{1}{t} \ln \frac{\|\boldsymbol{\delta}(t)\|}{\|\boldsymbol{\delta}_0\|}$$

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## Mean Exponential Growth of Nearby Orbits

Cincotta, P. and C. Simó, 2000, ApJ Sup. Ser., 147, 205

$$\lambda := \lim_{t \rightarrow \infty} \frac{1}{t} \int_0^t \frac{\dot{\delta}(s)}{\delta(s)} ds = \left\langle \frac{\dot{\delta}}{\delta} \right\rangle,$$

$$\delta = \|\delta\|, \quad \dot{\delta} = \frac{d}{dt} \delta = \frac{\dot{\delta} \cdot \delta}{\|\delta\|^2}.$$

$$Y(t) := \frac{2}{t} \int_0^t \frac{\dot{\delta}(s)}{\delta(s)} s ds, \quad \langle Y \rangle(t) := \frac{1}{t} \int_0^t Y(s) ds$$

# MEGNO properties

- 1 If  $\mathbf{x}(t, \mathbf{x}_0)$  is regular then

$$\lim_{t \rightarrow \infty} \langle Y \rangle(t) = 2.$$

- 2 If  $\mathbf{x}(t, \mathbf{x}_0)$  is chaotic then  $\langle Y \rangle(t) \approx (\lambda/2)t$  as  $t \rightarrow \infty$ .

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$$\frac{d}{dt}y = \frac{\dot{\boldsymbol{\delta}} \cdot \boldsymbol{\delta}}{\boldsymbol{\delta} \cdot \boldsymbol{\delta}}t, \quad \frac{d}{dt}w = 2\frac{y}{t}.$$

Then  $Y(t) = 2y(t)/t$  and  $\langle Y \rangle(t) = w(t)/t$ .

# Other even better methods

## Spectral Number

Michtchenko, T. and Ferraz-Mello, S. 2001, ApJ, 122, 474.

## Genetic Algorithm with MEGNO Penalty

- 1 Genetic algorithm, Charbonneau, P. 1995, ApJS, 101, 309.

<http://www.hao.ucar.edu/public/research/si/pikaia/pikaia.html>

- 2 MEGNO (or SN, or any other) penalty.
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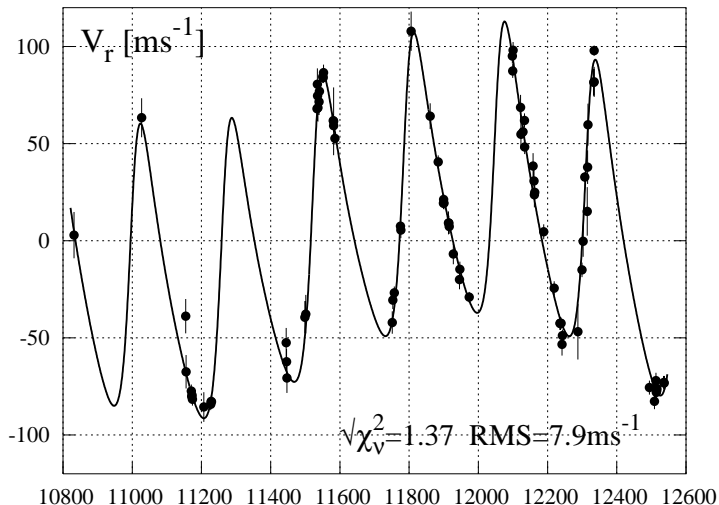
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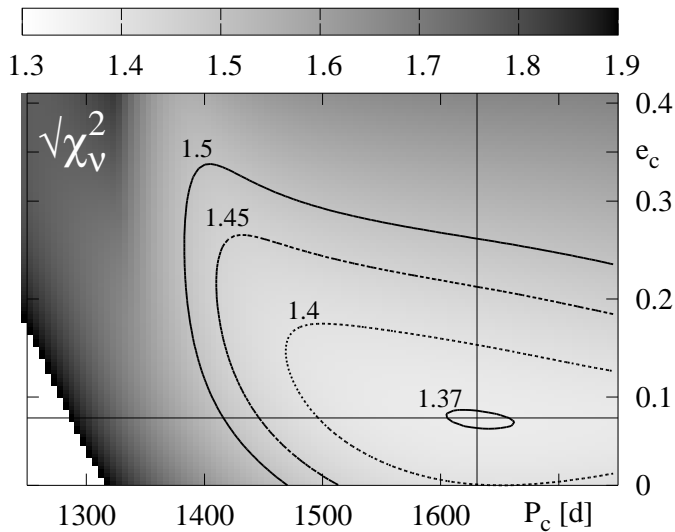
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# Observations

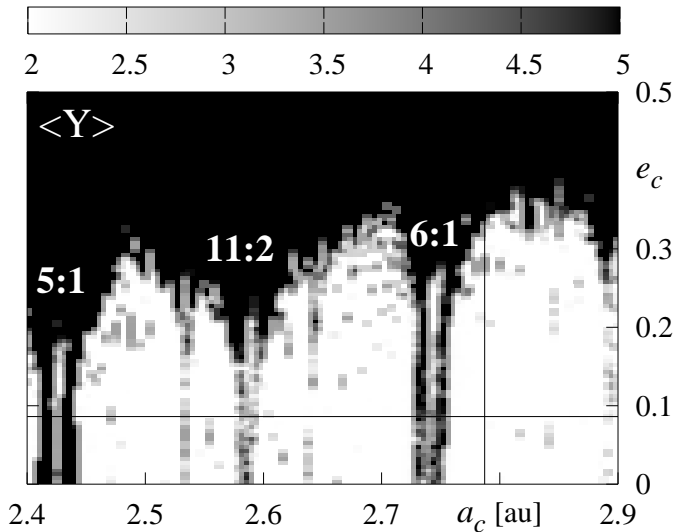
86 points;  $\sigma \approx 3 - 6\text{m/s}$  for Keck;  $\sigma \approx 7 - 17\text{m/s}$  for Lick.



# $\chi$ map



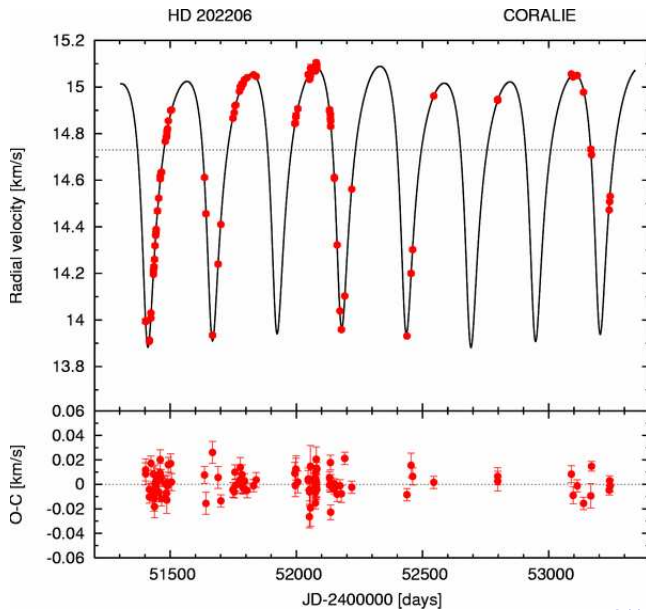
# Stability



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# RV curve

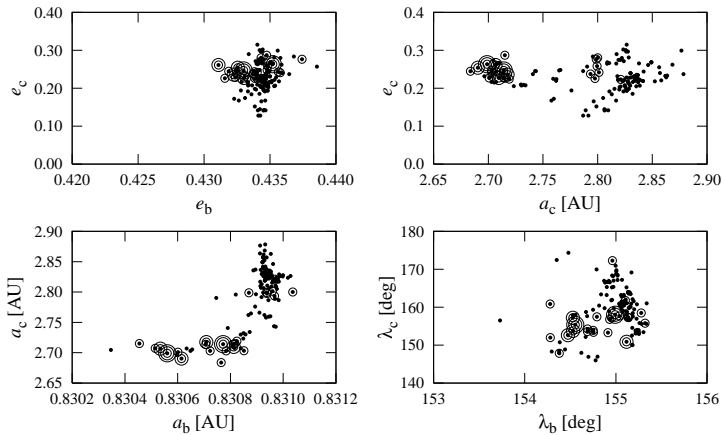




# Estimated parameters

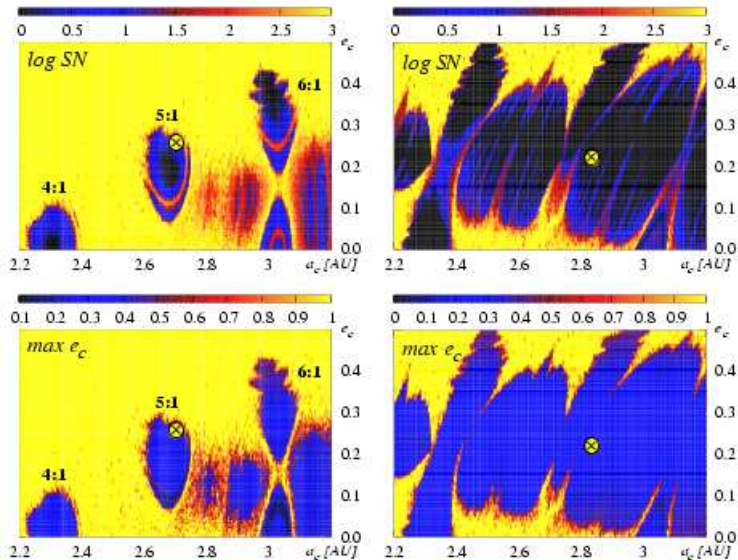
- $M_b = 17.5M_J$ ,  $M_c = 2.4M_J$ .
- $P_b = 256d$ ,  $P_c = 1297, 1383d$ .
- $e_b = 0.43$ ,  $e_c = 0.27$ .
- 5 : 1 MMR?
- Keplerian and Newtonian fits give rise desintegrating system ( $\approx 10^3 y$ )

# GAMP results

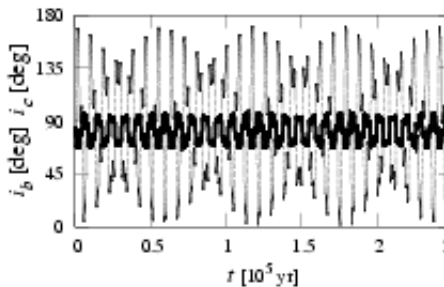
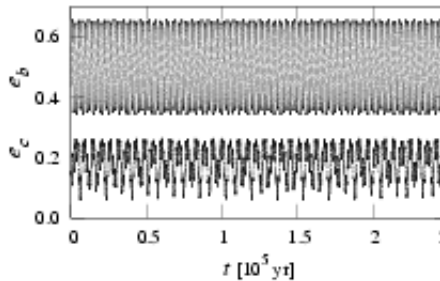
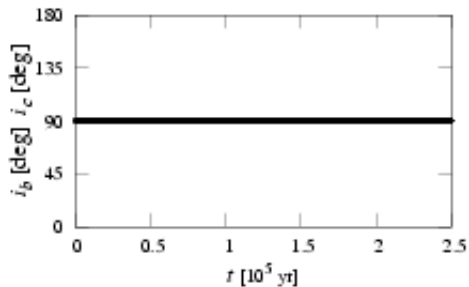
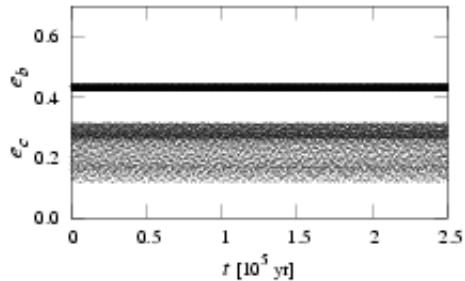


# GAMP results

left  $\chi_\nu = 1.53$ , rms = 9.97 m/s; right  $\chi_\nu = 1.62$ , rms = 10.32 m/s;



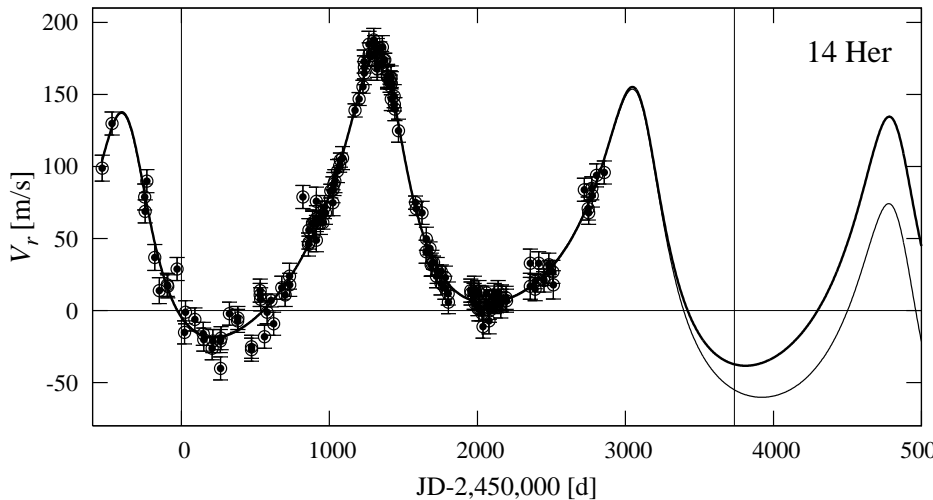
# Coplanar or not?



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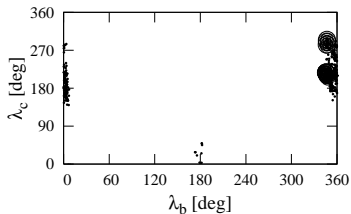
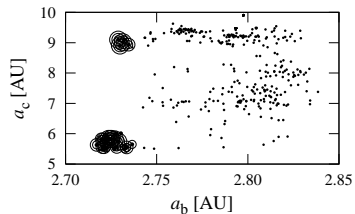
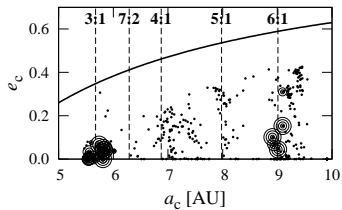
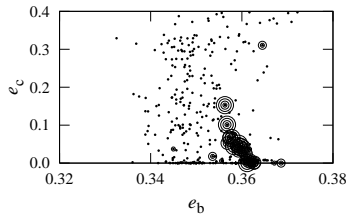
# RV curve



# Problem

- $M_b = 4.64M_J$ ,  $e_b = 0.34$ ,  $P_b = 1773d$  and linear trend  $3.6m/s$  per year.
- best Keplerian+drift fits: rms=  $11m/s$  but mean error of observations  $\sigma_m = 7.2m/s$ .

# GAMP results





# New updated analysis

K. Gozdziwski, C. Migaszewski, M. Konacki, arXiv:0705.1858

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- 2001 Butler et al.,  $P_b \approx 630\text{d}$ .
- 2002 Jones et al., a linear trend.
- 2004 McCarthy et al. ,  $P_c \approx 3000\text{d}$ ,  $e_c = 0.57$ .
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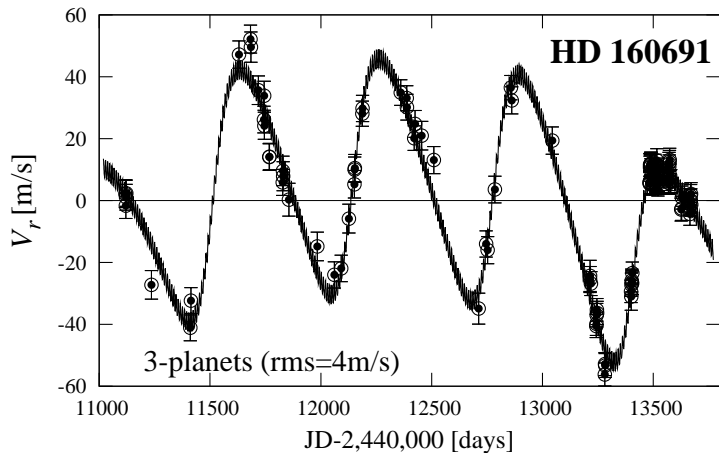
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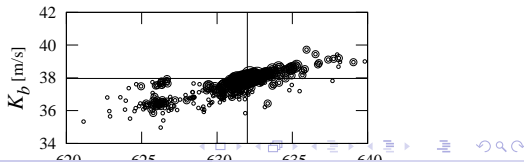
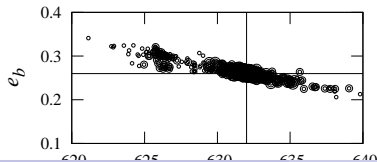
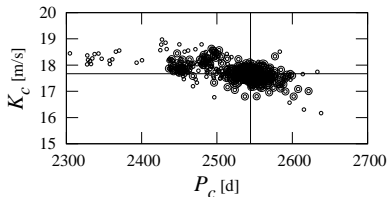
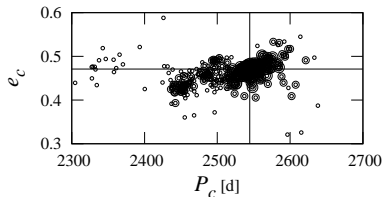
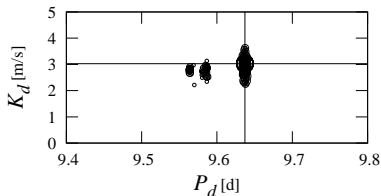
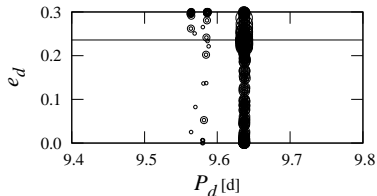
# RV curve





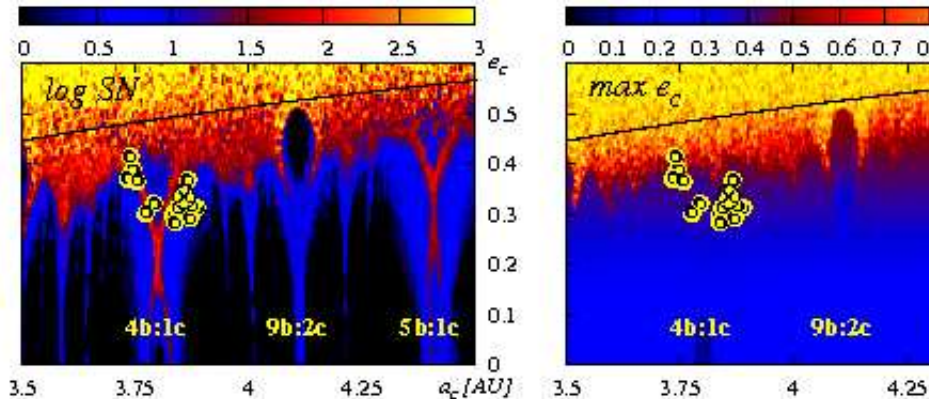
# 3 Keplerian planets+ GA

$e_c = 0.47$  strong unstable solutions.

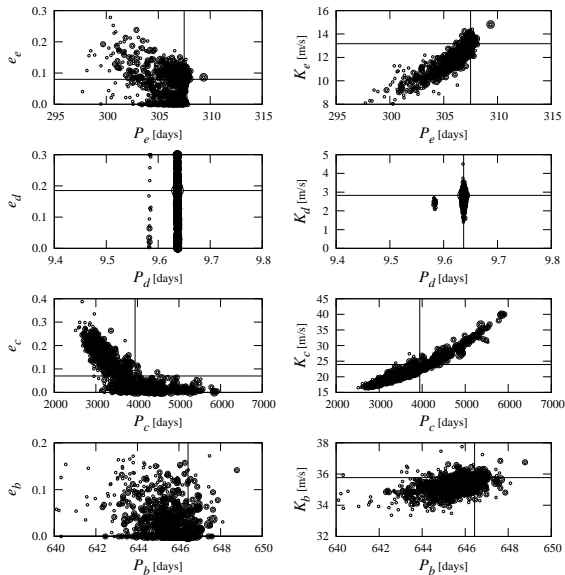


## 2(3) planets+ GAMP

2004 McCarthy et al. observations: for stable solutions  $a_c > 4\text{AU}$ .



# 4 Keplerian planets+ GA



stable solutions

# Much more in

- 1 Goźdzowski, K. et. al. 2007, ApJ, 657, pp. 546-558.
- 2 Pepe, F. et. al. 2007, A& A, 426, pp. 769-776; different observations and similar conclusions.

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# Assumptions of simulations

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- 3 Parametrisation: Keplerian elements, initial conditions;
- 4  $t_j$  random.
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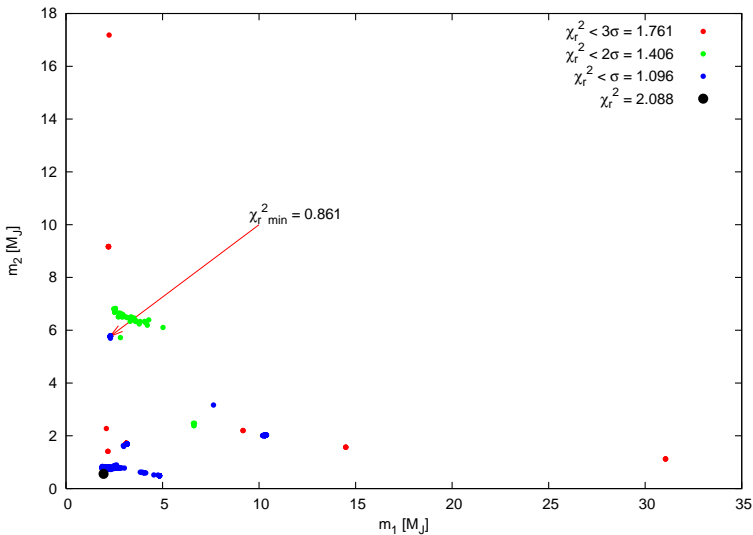
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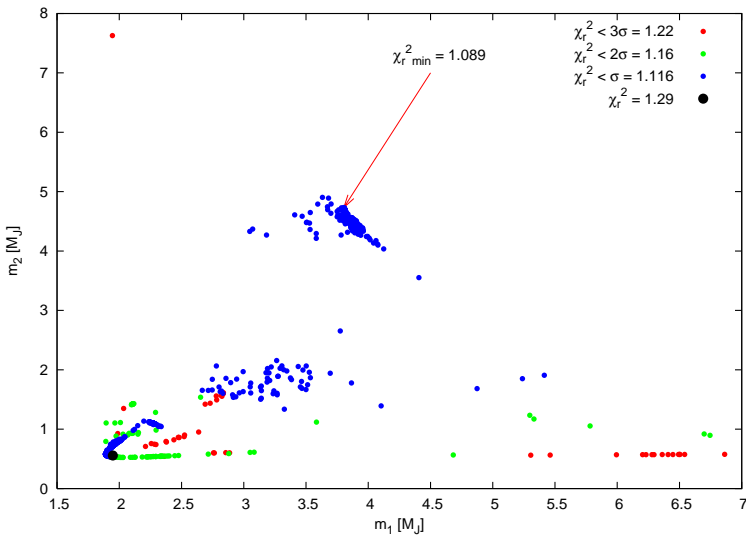
# 2:1 MMR, $2P_2$

$N_{\text{obs}} = 20$



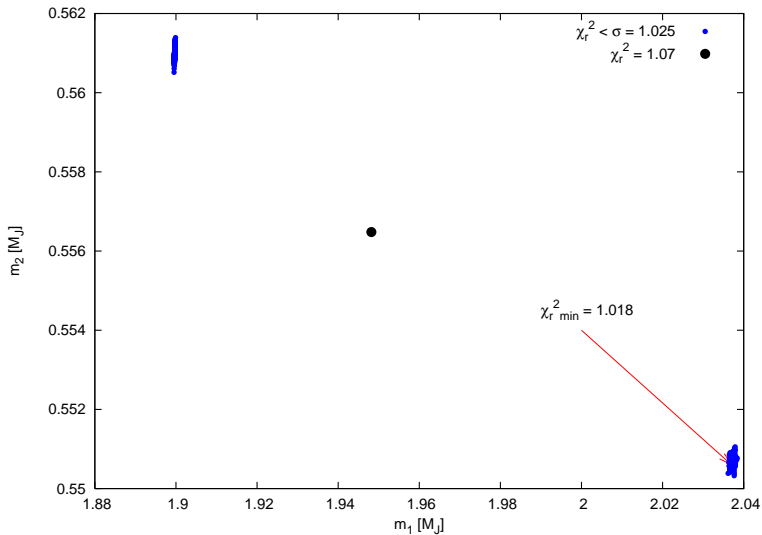
# 2:1 MMR, $5P_2$

$N_{\text{obs}} = 54$



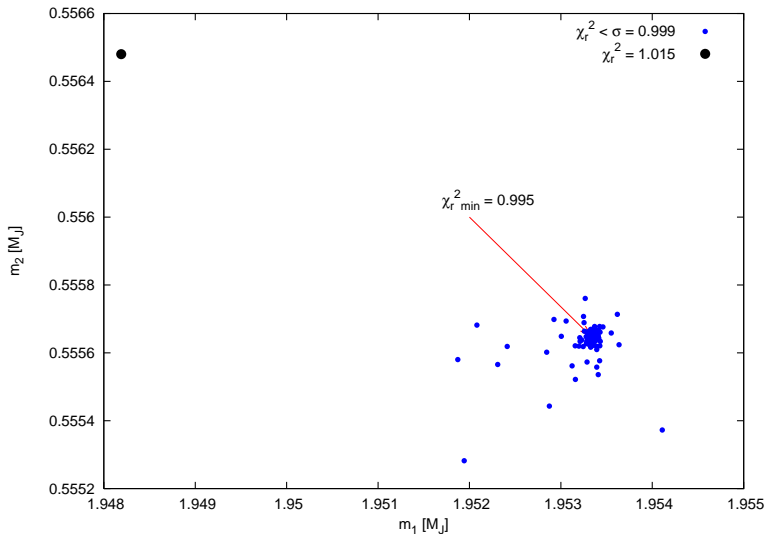
# 2:1 MMR, $15P_2$

$N_{\text{obs}} = 161$



# 2:1 MMR, $30P_2$

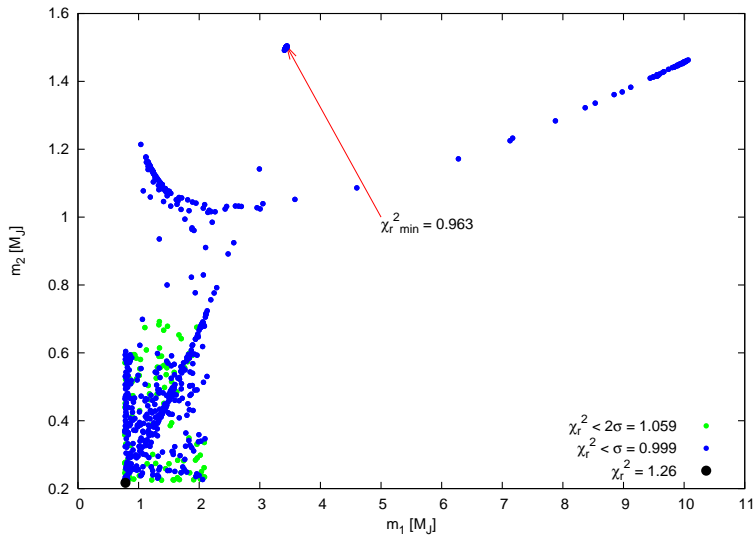
$N_{\text{obs}} = 325$





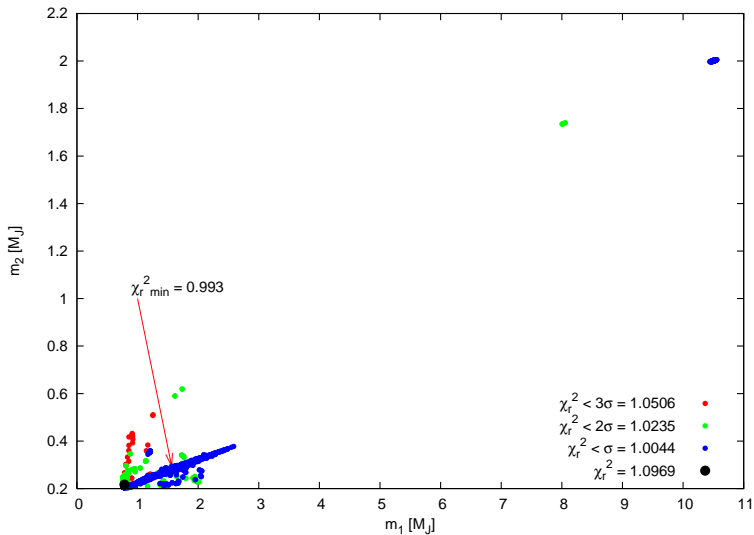
# 3:1 MMR, $2P_2$

$N_{\text{obs}} = 47$



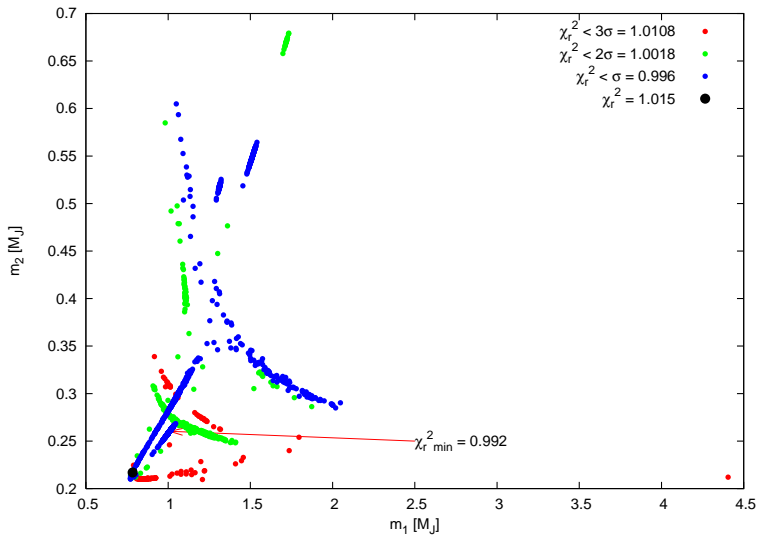
# 3:1 MMR, $5P_2$

$N_{\text{obs}} = 115$



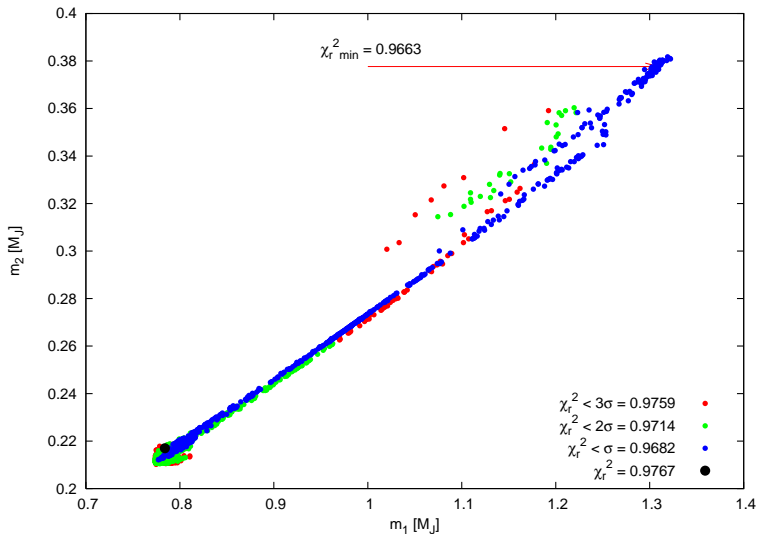
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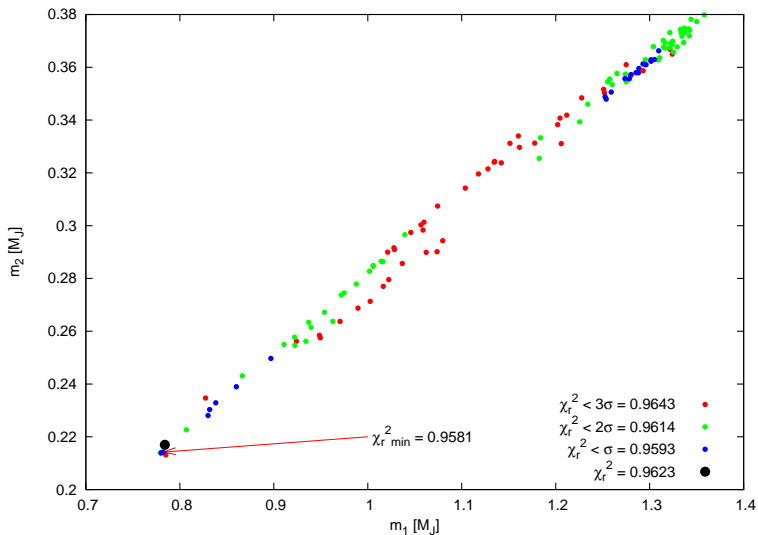
# 3:1 MMR, $30P_2$

$N_{\text{obs}} = 650$



# 3:1 MMR, $100P_2$

$N_{\text{obs}} = 1000$



# References

- 1 Godziewski, Krzysztof; Maciejewski, Andrzej J.; Migaszewski, Cezary, ApJ, 651, pp. 546-558.
- 2 Godziewski, Krzysztof; Maciejewski, Andrzej J.; Migaszewski, Cezary, eprint arXiv:astro-ph/0608279
- 3 Goździewski, Krzysztof; Konacki, Maciej; Maciejewski, Andrzej J., ApJ., 645, 688-703.
- 4 Goździewski, Krzysztof; Konacki, Maciej; Maciejewski, Andrzej J., ApJ., 622, 1136-1148.
- 5 Goździewski, Krzysztof; Konacki, Maciej; Maciejewski, Andrzej J., ApJ., 594, 1019-1032.

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